

# pySECDEC: A Toolbox for the Numerical Evaluation of multi-scale Integrals

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## What is pySECDEC?

successor of SECDEC-3

*S. Borowka, G. Heinrich, S. P. Jones, M. Kerner, J. Schlenk, T. Zirke* [1502.06595]

Numerically computes regulated parameter integrals of the form

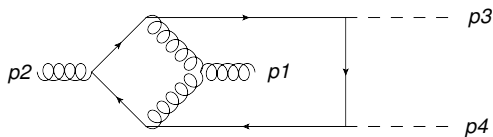
$$\mathcal{I} \equiv \int_0^1 dx_1 \dots \int_0^1 dx_N \prod_{i=1}^m f_i(\vec{x}, \vec{a})^{b_i + \sum_k c_{ik} \epsilon_k}$$

where the  $f_i$  are polynomials. Typically:  $\mathcal{I}|_{\epsilon_k=0} = \infty$ .

Example:

Loop integrals

after Feynman parametrization



## The SECDEC collaboration

Sophia Borowka

Gudrun Heinrich

Stephan Jahn

Stephen Jones

Matthias Kerner

Johannes Schlenk

## former members

Thomas Binoth

Jonathon Carter

Tom Zirke

## Paper

[1703.09692] submitted to CPC

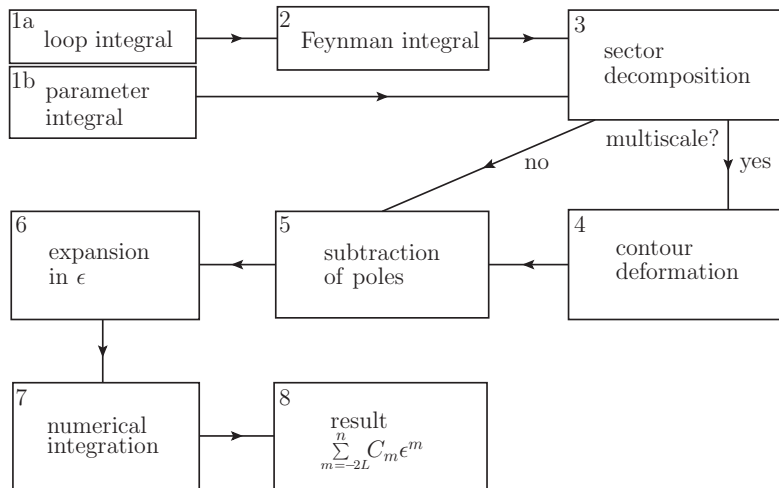
## Homepage

<http://secdec.hepforge.org/>

## Other Implementations

- *C. Bogner, S. Weinzierl*  
**Sector decomposition**  
[0709.4092]
- *A.V. Smirnov*  
**FIESTA 4**  
[1511.03614]

## Flowchart



## Loop Integral - Momentum Representation

$$\mathcal{I} = \int d^D k_1 \cdot \dots \cdot d^D k_L \frac{1}{P_1^{\nu_1} \cdot \dots \cdot P_N^{\nu_N}}$$

$D$ : dimensionality

$L$ : number of loops

$N$ : number of propagators

$P_i$ : propagators ( $\langle momentum \rangle^2 [- \langle mass \rangle^2] + i\delta$ )

$\nu_i$ : propagator powers

## Loop Integral - Feynman Representation

$$\mathcal{I} = (-1)^{N_\nu} \frac{\Gamma(N_\nu - LD/2)}{\prod_{j=1}^N \Gamma(\nu_j)} \int_0^1 \prod_{j=1}^N dx_j x_j^{\nu_j-1} \delta\left(1 - \sum_{n=1}^N x_n\right) \frac{\mathcal{U}^{N_\nu - (L+1)D/2}}{\mathcal{F}^{N_\nu - LD/2}}$$

$D$ : dimensionality

$L$ : number of loops

$N$ : number of propagators

$\nu_i$ : propagator powers

$$N_\nu = \sum_{i=1}^N \nu_i$$

$\mathcal{U} = \mathcal{U}(\vec{x})$ : 1<sup>st</sup> Symanzik polynomial

$\mathcal{F} = \mathcal{F}(\vec{x}, p_i \cdot p_j, m_i^2)$ : 2<sup>nd</sup> Symanzik polynomial

## Feynman Parametrization with pySECDEC

```

1  >>> from pySecDec.loop_integral import
    ↪ LoopIntegralFromPropagators
2
3  >>> one_loop_bubble =
    ↪ LoopIntegralFromPropagators(
4  ...   propagators=['k^2-m^2', '(k-p)^2'],
5  ...   loop_momenta=['k']
6  ... )
7
8  >>> one_loop_bubble.exponentiated_U
9  ( + (1)*x0 + (1)*x1)**(2*eps - 2)
10
11 >>> one_loop_bubble.exponentiated_F
12 ( + (m**2 - p**2)*x0*x1 +
    ↪ (m**2)*x0**2)**(-eps)
13
14 >>> one_loop_bubble.Gamma_factor
15 gamma(eps)

```

```

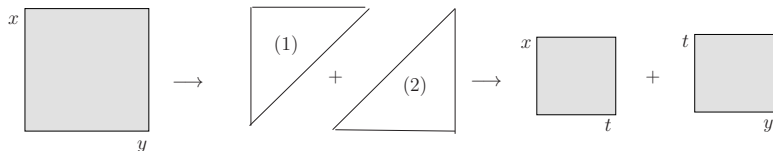
1  >>> from pySecDec.loop_integral import
    ↪ LoopIntegralFromGraph, plot_diagram
2
3  >>> one_loop_bubble = LoopIntegralFromGraph(
4  ...   internal_lines=[('m', (1,2)], [(0, (1,2))],
5  ...   external_lines=[('p', 1), ('q', 2)],
6  ...   replacement_rules=[('q', 'p')]
7  ... )
8
9  >>> one_loop_bubble.exponentiated_U
10 ( + (1)*x0 + (1)*x1)**(2*eps - 2)
11
12 >>> one_loop_bubble.exponentiated_F
13 ( + (m**2 - p**2)*x0*x1 +
    ↪ (m**2)*x0**2)**(-eps)
14
15 >>> one_loop_bubble.Gamma_factor
16 gamma(eps)
17
18 >>> plot_diagram(
19 ...   one_loop_bubble.internal_lines,
20 ...   one_loop_bubble.external_lines,
21 ...   filename='bubble1L',
22 ...   Gstart=986089
23 ... )

```



## Sector Decomposition

or: Resolution of Overlapping Singularities



$$\begin{aligned}
 & \int_0^1 dx \int_0^1 dy (x+y)^{a+b\epsilon} f(x, y) \\
 &= \int_0^1 dx \int_0^1 dy (x+y)^{a+b\epsilon} f(x, y) \left[ \underbrace{\Theta(x-y)}_{(1)} + \underbrace{\Theta(y-x)}_{(2)} \right] \\
 &= \int_0^1 dx \int_0^1 dt x x^{a+b\epsilon} (1+t)^{a+b\epsilon} f(x, xt) + \int_0^1 dt \int_0^1 dy y y^{a+b\epsilon} (t+1)^{a+b\epsilon} f(yt, y)
 \end{aligned}$$



## Sector Decomposition

or: Resolution of Overlapping Singularities

```

1  >>> import pySecDec as psd
2
3  >>> # define the integration variables
4  >>> integration_variables = ['x', 'y']
5
6  >>> # define the polynomial to be decomposed
7  >>> poly = psd.algebra.Expression('(x+y) ** (a+b*eps)', integration_variables)
8
9  >>> # keep track of variable transformations
10 >>> x = psd.algebra.Expression('x', integration_variables)
11 >>> y = psd.algebra.Expression('y', integration_variables)
12
13 >>> # initialize the decomposition
14 >>> initial_sector = psd.decomposition.Sector([poly], [x,y])
15 >>> print(initial_sector)
16 Sector:
17 Jacobian= + (1)
18 cast=[(( + (1))**(+ (a + b*eps))) * (( + (1)*x + (1)*y)**(+ (a + b*eps)))]
19 other=[ + (1)*x, + (1)*y]
20
21 >>> # perform the decomposition
22 >>> for sector in psd.decomposition.iterative.iterative_decomposition(initial_sector):
23 ...     print(sector)
24 ...     print()
25 Sector:
26 Jacobian= + (1)*x
27 cast=[(( + (1)*x)**(+ (a + b*eps))) * (( + (1) + (1)*y)**(+ (a + b*eps)))]
28 other=[ + (1)*x, + (1)*x*y]
29
30 Sector:
31 Jacobian= + (1)*y
32 cast=[(( + (1)*y)**(+ (a + b*eps))) * (( + (1)*x + (1))**(+ (a + b*eps)))]
33 other=[ + (1)*x*y, + (1)*y]

```

## Subtraction of Poles

$$\begin{aligned}
 & \int_0^1 dt t^{-1+b\epsilon} g(t) \\
 &= \int_0^1 dt t^{-1+b\epsilon} (g(0) + g(t) - g(0)) \\
 &= \underbrace{\int_0^1 dt t^{-1+b\epsilon} g(0)}_{=\frac{1}{b\epsilon} g(0)} + \underbrace{\int_0^1 dt t^{-1+b\epsilon} (g(t) - g(0))}_{\text{finite for } \epsilon \rightarrow 0, \text{ expand integrand in } \epsilon}
 \end{aligned}$$

## Subtraction of Poles

```

1  >>> import pySecDec as psd
2  >>> import sympy as sp
3
4  >>> # define the essential symbols
5  >>> integration_variables = ['t']
6  >>> regulators = ['eps']
7  >>> symbols = integration_variables + regulators
8
9  >>> # define "t^(-1 + b*eps)" and "g(t)"
10 >>> t_monomial = psd.algebra.Expression('t**(-1 + b*eps)', symbols)
11 >>> g = psd.algebra.Expression('g(t)', symbols)
12
13 >>> # pack the monomial (can have more than one in general)
14 >>> monomials = psd.algebra.Product(t_monomial)
15
16 >>> # need an initializer for the pole part
17 >>> polynomial_one = psd.algebra.Polynomial.from_expression(1, symbols)
18 >>> pole_part_initializer = psd.algebra.Pow(polynomial_one, -polynomial_one)
19
20 >>> # perform the subtraction
21 >>> subtraction_initializer = psd.algebra.Product(monomials, pole_part_initializer, g)
22 >>> subtracted = psd.subtraction.integrate_pole_part(subtraction_initializer, 0)
23
24 >>> # pretty representation
25 >>> for term in subtracted:
26 ...     print(sp.sympify(term))
27 g(0)/(b*eps)
28 t**(b*eps - 1)*(-g(0) + g(t))
29
30 >>> # internal representation
31 >>> subtracted
32 [((( + (1))**(( + (b)*eps + (-1)))) * (( + (b)*eps) ** ( + (-1))) * ((g( + (0))))),
33  ((( + (1)*t)**(( + (b)*eps + (-1)))) * (( + (1)) ** ( + (-1))) * ((g(+ (1)*t) + (( + (-1)) * (g( + (0))))))]

```

## Contour Deformation - A Simple Example

consider the massive one loop bubble



$$\int d^D k \frac{1}{(k^2 - m^2) \left( (k - p)^2 - m^2 \right)}$$

taking  $\delta(1 - x_1 - x_2)$  into account:

$$\begin{aligned} \mathcal{F}(\vec{x}, p_i \cdot p_j, m_i^2) &= \left[ m^2 (x_1 + x_2)^2 - p^2 x_1 x_2 \right]_{x_2=1-x_1} \\ &= m^2 - p^2 x_1 (1 - x_1) \end{aligned}$$

- ▶ physical threshold  $p^2 \geq 4m^2$
- ▶ can have  $\mathcal{F} = 0$  although  $x_1 \neq 0$

## Contour Deformation

or: Satisfying the Feynman Prescription

$$\begin{aligned} \mathcal{I} &= \int d^D k_1 \cdot \dots \cdot d^D k_L \frac{1}{P_1^{\nu_1} \cdot \dots \cdot P_N^{\nu_N}} \\ &= (-1)^{N_\nu} \frac{\Gamma(N_\nu - LD/2)}{\prod_{j=1}^N \Gamma(\nu_j)} \int_0^1 \prod_{j=1}^N dx_j x_j^{\nu_j-1} \delta\left(1 - \sum_{n=1}^N x_n\right) \frac{\mathcal{U}^{N_\nu - (L+1)D/2}}{\mathcal{F}^{N_\nu - LD/2}} \end{aligned}$$

$P_i$ : propagators ( $\langle \text{momentum} \rangle^2 [-\langle \text{mass} \rangle^2] + \boxed{i\delta}$ )

$\mathcal{F} = \mathcal{F}(\vec{x}, p_i \cdot p_j, m_i^2) - \boxed{i\delta}$ : 2<sup>nd</sup> Symanzik polynomial

## Contour Deformation

or: Satisfying the Feynman Prescription

$$\mathcal{F}(\vec{x}, p_i \cdot p_j, m_i^2) - \boxed{i\delta}$$

move integration contour to the complex plane

$$\begin{aligned} \vec{z}: [0, 1]^n &\longrightarrow \mathbb{C}^n \\ x_k &\rightarrow z_k(\vec{x}) \\ &\equiv x_k - i\lambda_k x_k (1 - x_k) \frac{\partial \operatorname{Re}[\mathcal{F}(\vec{x})]}{\partial x_k} \end{aligned}$$

such that

$$\operatorname{Im}[\mathcal{F}(\vec{z}(\vec{x}))] \leq \operatorname{Im}[\mathcal{F}(\vec{x})] \quad \forall \vec{x} \in [0, 1]^n$$

## Contour Deformation

or: Satisfying the Feynman Prescription

$$\begin{aligned}
 \mathcal{F}(\vec{z}(\vec{x})) &= + \operatorname{Re} \mathcal{F}(\vec{x}) + i \operatorname{Im} \mathcal{F}(\vec{x}) \\
 &+ \sum_k \lambda_k \left[ -i \left( \frac{\partial \operatorname{Re} \mathcal{F}(\vec{x})}{\partial x_k} \right)^2 + \frac{\partial \operatorname{Re} \mathcal{F}(\vec{x})}{\partial x_k} \frac{\partial \operatorname{Im} \mathcal{F}(\vec{x})}{\partial x_k} \right] x_k (1 - x_k) \\
 &+ \sum_{k,l} \frac{\lambda_k \lambda_l}{2} \left[ -\frac{\partial^2 \operatorname{Re} \mathcal{F}(\vec{x})}{\partial x_k \partial x_l} - i \frac{\partial^2 \operatorname{Im} \mathcal{F}(\vec{x})}{\partial x_k \partial x_l} \right] \prod_{i=k,l} \frac{\partial \operatorname{Re} \mathcal{F}(\vec{x})}{\partial x_i} x_i (1 - x_i) \\
 &+ \mathcal{O}(\lambda^3)
 \end{aligned}$$

- ▶ correct sign at  $\mathcal{O}(\lambda)$
- ▶ indeterminate sign at  $\mathcal{O}(\lambda^2)$

**correct sign if  $\lambda_k$  “small enough”**

## Expansion in the Regulator(s) $\epsilon$

- ▶ conceptually easy
- ▶ Taylor expansion and series multiplication

poles in  $\epsilon$  explicitly factorize by construction

- ▶ cumbersome bookkeeping

individual factors must be expanded to different orders

## Numerical Integration

- ▶ uses CUBA integrator library by default (except 1D)

*T. Hahn* [hep-ph/0404043]

- ▶ `gsl_integration_cquad` (GNU scientific library) for 1D
- ▶ can link any numerical integrator using the C++ interface



## Basic Usage

$$\int_0^1 dx \int_0^1 dy (x+y)^{-2+\epsilon} = \frac{1}{\epsilon} + (1 - \log(2)) + O(\epsilon) \approx \frac{1}{\epsilon} + 0.306853 + O(\epsilon)$$

## Step 1: write input files

### generate\_easy.py

```

1  from pySecDec import make_package
2
3  make_package(
4
5  name = 'easy',
6  integration_variables = ['x','y'],
7  regulators = ['eps'],
8
9  requested_orders = [0],
10 polynomials_to_decompose = ['(x+y)^(-2+eps)'],
11 )
12

```

### integrate\_easy.py

```

1  from pySecDec.integral_interface \
2      import IntegralLibrary
3
4  # load c++ library
5  easy_integral = \
6      IntegralLibrary('easy/easy_pylink.so')
7
8  # integrate
9  _, _, result = easy_integral()
10
11 # print result
12 print('Numerical Result:')
13 print(result)

```

## Step 2: run pySECDEC

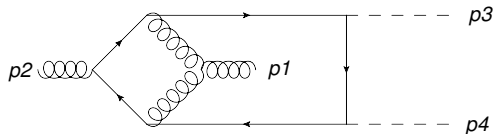
```

1  $ python generate_easy.py && make -C easy && python integrate_easy.py
2  <skipped some output>
3  Numerical Result:
4  + (1.00015897181235158e+00 +/- 4.03392522752491021e-03)*eps^-1 + (3.06903035514056399e-01 +/-
   ↪ 2.82319349818329918e-03) + 0(eps)

```

## Application: Higgs Boson Pair Production

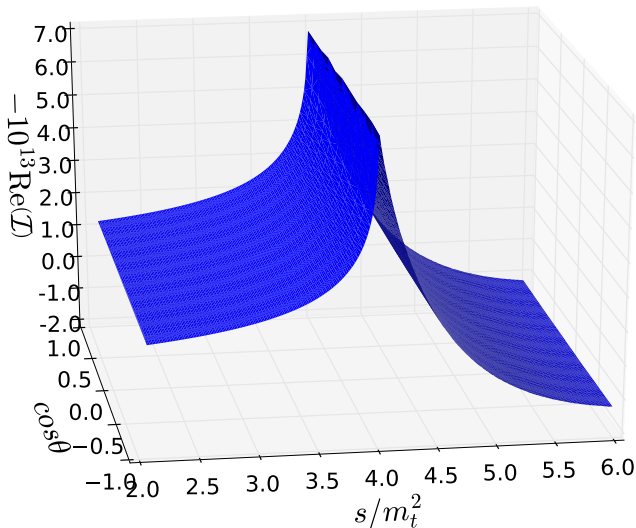
S. Borowka, N. Greiner, G. Heinrich, S. P. Jones, M. Kerner, J. Schlenk, T. Zirke [1608.04798]



$$\mu^{-6-4\epsilon} \mathcal{I} \equiv \text{finite}, \quad \mu = 1\text{GeV}$$

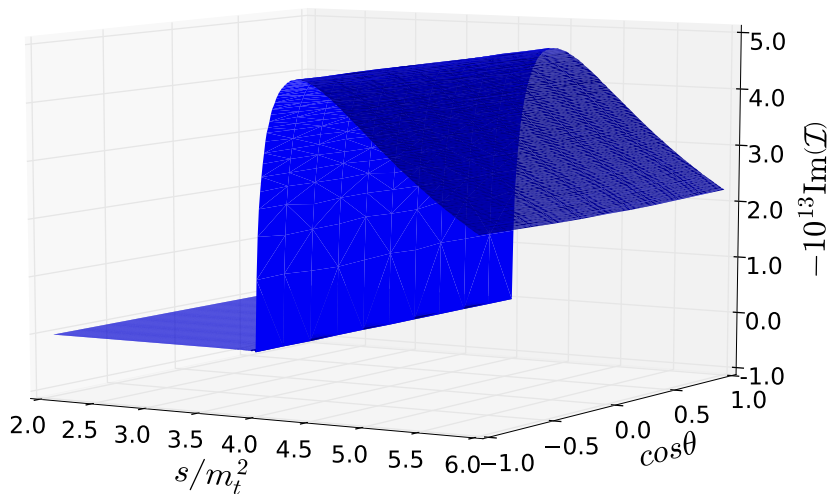
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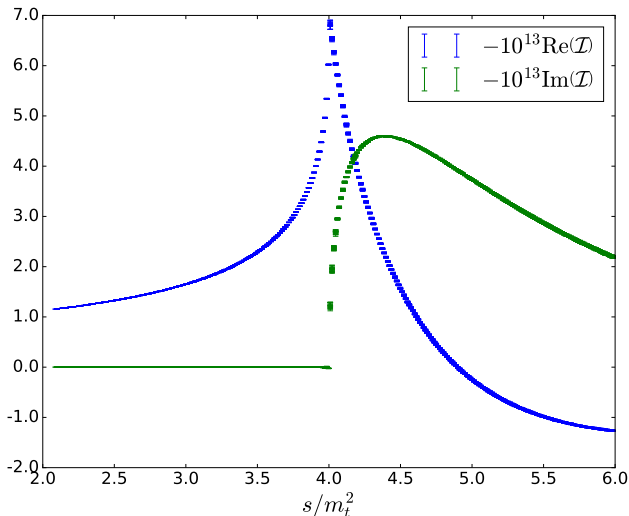
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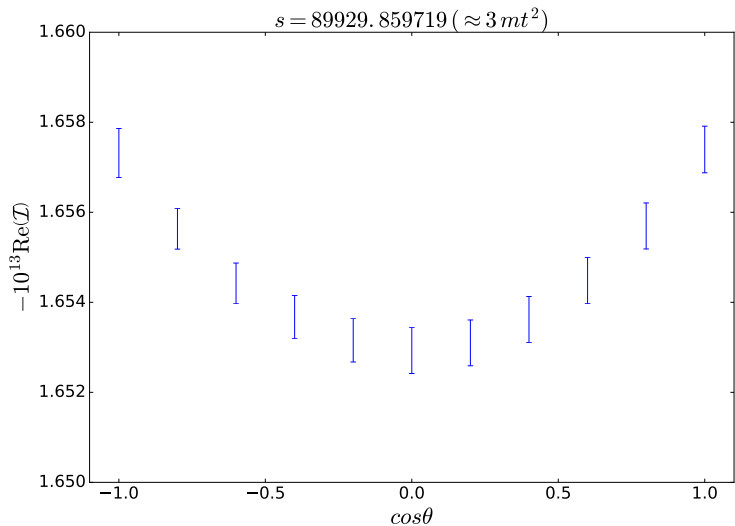
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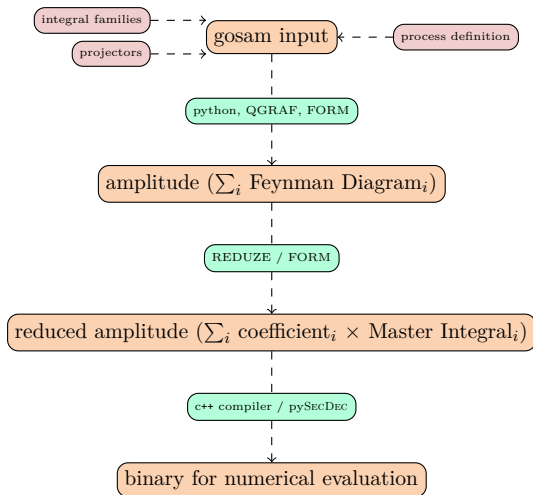


## Application: Higgs Boson Pair Production

S. Borowka, N. Greiner, G. Heinrich, S. P. Jones, M. Kerner, J. Schlenk, T. Zirke [1608.04798]



## Application: GoSAM-Xloop



## The GoSAM-Xloop collaboration

Nicolas Greiner  
 Gudrun Heinrich  
 Stephan Jahn  
 Stephen Jones  
 Matthias Kerner  
 et al.

## New Features in pySECDEC

- ▶ fully relying on open-source software
- ▶ generates a C++ library suitable for amplitude calculations
- ▶ supports more general tensor numerators
- ▶ supports multiple regulators
- ▶ can handle integrals without Euclidean region
- ▶ faster numerics due to **Code Optimization in FORM**  
*J. Kuipers, T. Ueda, J.A.M. Vermaseren [1310.7007]*
- ▶ can handle integrals without Euclidean region
- ▶ extended checks of the deformed integration contour

## Coming Soon

- ▶ quasi monte carlo (qmc) integrator
- ▶ numerical integration on GPUs using CUDA



# Summary

introduction to the Sector Decomposition approach  
as implemented in pySECDEC (<http://secdec.hepforge.org/>)

- ▶ description of the method
- ▶ pySECDEC code examples
- ▶ application in  $gg \rightarrow HH$  [1608.04798]
- ▶ application in amplitude generator GoSAM-Xloop  
(unpublished)

# BACKUP

## Timings

Table 5  
Comparison of timings (algebraic, numerical) using pySECDEC, SECDEC 3 and FIESTA 4.1.

	pySECDEC time (s)	SECDEC 3 time (s)	FIESTA 4.1 time (s)
triangle2L	(40.5, 9.6)	(56.9, 28.5)	(211.4, 10.8)
triangle3L	(110.1, 0.5)	(131.6, 1.5)	(48.9, 2.5)
elliptic2L_euclidean	(8.2, 0.2)	(4.2, 0.1)	(4.9, 0.04)
elliptic2L_physical	(21.5, 1.8)	(26.9, 4.5)	(115.3, 4.4)
box2L_invprop	(345.7, 2.8)	(150.4, 6.3)	(21.5, 8.8)

## Basic Usage - Analytical Calculation

$$\begin{aligned}
& \int_0^1 dx \int_0^1 dy (x+y)^{-2+\epsilon} \\
&= 2 \int_0^1 dx x^{-1+\epsilon} \int_0^1 dt (1+t)^{-2+\epsilon} \\
&= \frac{2}{\epsilon} \left[ \int_0^1 dt (1+t)^{-2} + \epsilon \int_0^1 dt (1+t)^{-2} \log(1+t) + O(\epsilon^2) \right] \\
&= \frac{2}{\epsilon} \left[ \frac{1}{2} + \epsilon \frac{1}{2} (1 - \log(2)) + O(\epsilon^2) \right] = \frac{1}{\epsilon} + (1 - \log(2)) + O(\epsilon)
\end{aligned}$$

# pySECDEC: A Toolbox to Evaluate multi-scale Integrals

