Samuel Kováčik, Dublin Institute for Advanced Studies with Denjoe O' Connor and Yuhma Asano (and Veselin Filev)







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ICHEC Irish Centre for High-End Computing I promise!





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Phase transition or phase transitions?



Samuel Kováčik: Phase transition(s) of the bosonic BMN model





$$S_E = \frac{1}{g^2} \int d\tau \operatorname{Tr}\left(\frac{1}{2} (D_\tau X^i)^2 - \frac{1}{4} [X^i, X^j]^2 + \frac{1}{2} \psi^T C_9 D_\tau \psi - \frac{1}{2} \psi^T C_9 \gamma^i [X^i, \psi]\right)$$

$$S_E = \frac{1}{g^2} \int d\tau \,\mathrm{Tr}\left(\frac{1}{2} (D_\tau X^i)^2 - \frac{1}{4} [X^i, X^j]^2\right)$$

$$S_E = \frac{1}{g^2} \int d\tau \, \text{Tr}\left(\frac{1}{2} (D_\tau X^i)^2 - \frac{1}{4} [X^i, X^j]^2\right)$$





BD model

$$\begin{aligned} \mathsf{BD} \ \mathsf{model} \\ S_E &= N \int_0^\beta d\tau \left[\operatorname{Tr} \left(\frac{1}{2} D_\tau X^a D_\tau X^a + \frac{1}{2} D_\tau \bar{X}^{\rho \dot{\rho}} D_\tau X_{\rho \dot{\rho}} + \frac{1}{2} \lambda^{\dagger \rho} D_\tau \lambda_{\rho} + \frac{1}{2} \theta^{\dagger \dot{\rho}} D_\tau \theta_{\dot{\rho}} \right) \\ &+ \operatorname{tr} \left(D_\tau \bar{\Phi}^\rho D_\tau \Phi_\rho + \chi^\dagger D_\tau \chi \right) \\ &- \operatorname{Tr} \left(\frac{1}{4} [X^a, X^b]^2 + \frac{1}{2} [X^a, \bar{X}^{\rho \dot{\rho}}] [X^a, X_{\rho \dot{\rho}}] \right) \\ &+ \frac{1}{2} \operatorname{Tr} \sum_{A=1}^3 \mathcal{D}^A \mathcal{D}^A + \operatorname{tr} \left(\bar{\Phi}^\rho (X^a - m^a)^2 \Phi_\rho \right) \\ &- \operatorname{Tr} \left(-\frac{1}{2} \lambda^{\dagger \rho} \gamma^a [X^a, \lambda_{\rho}] + \frac{1}{2} \theta^{\dagger \dot{\rho}} \gamma^a [X^a, \theta_{\dot{\rho}}] - \sqrt{2} i \varepsilon^{\rho \sigma} \theta^{\dagger \dot{\rho}} [X_{\sigma \dot{\rho}}, \lambda_{\rho}] \right) \\ &- \operatorname{tr} \left(\chi^{\dagger} \gamma^a (X^a - m^a) \chi + \sqrt{2} i \varepsilon^{\rho \sigma} \chi^{\dagger} \lambda_{\rho} \Phi_\sigma + \sqrt{2} i \varepsilon_{\rho \sigma} \bar{\Phi}^\rho \lambda^{\dagger \sigma} \chi \right) \right] \end{aligned}$$

$$\begin{split} \mathsf{BD} \ \mathsf{model} \\ S_E &= N \int_0^\beta d\tau \left[\mathrm{Tr} \left(\frac{1}{2} D_\tau X^a D_\tau X^a + \frac{1}{2} D_\tau \bar{X}^{\rho \dot{\rho}} D_\tau X_{\rho \dot{\rho}} + \frac{1}{2} \lambda^{\dagger \rho} D_\tau \lambda_{\rho} + \frac{1}{2} \theta^{\dagger \dot{\rho}} D_\tau \theta_{\dot{\rho}} \right) \\ &+ \mathrm{tr} \left(D_\tau \bar{\Phi}^\rho D_\tau \Phi_\rho + \chi^\dagger D_\tau \chi \right) \\ &- \mathrm{Tr} \left(\frac{1}{4} [X^a, X^b]^2 + \frac{1}{2} [X^a, \bar{X}^{\rho \dot{\rho}}] [X^a, X_{\rho \dot{\rho}}] \right) \\ &+ \frac{1}{2} \mathrm{Tr} \sum_{A=1}^3 \mathcal{D}^A \mathcal{D}^A + \mathrm{tr} \left(\bar{\Phi}^\rho (X^a - m^a)^2 \Phi_\rho \right) \\ &- \mathrm{Tr} \left(-\frac{1}{2} \lambda^{\dagger \rho} \gamma^a [X^a, \lambda_\rho] + \frac{1}{2} \theta^{\dagger \dot{\rho}} \gamma^a [X^a, \theta_{\dot{\rho}}] - \sqrt{2} i \varepsilon^{\rho \sigma} \theta^{\dagger \dot{\rho}} [X_{\sigma \dot{\rho}}, \lambda_\rho] \right) \\ &- \mathrm{tr} \left(\chi^\dagger \gamma^a (X^a - m^a) \chi + \sqrt{2} i \varepsilon^{\rho \sigma} \chi^\dagger \lambda_\rho \Phi_\sigma + \sqrt{2} i \varepsilon_{\rho \sigma} \bar{\Phi}^\rho \lambda^{\dagger \sigma} \chi \right) \bigg] \end{split}$$

Samuel Kováčik, Phase transition(s) of the bosonic BMN model

BD model



BMN model

$$\begin{split} S[X,\psi] &= N \int_{0}^{\beta} d\tau \operatorname{Tr} \left[\frac{1}{2} D_{\tau} X^{i} D_{\tau} X^{i} - \frac{1}{4} \left([X^{r},X^{s}] + \frac{i\mu}{3} \varepsilon^{rst} X_{t} \right)^{2} \right. \\ &\left. - \frac{1}{2} [X^{r},X^{m}]^{2} - \frac{1}{4} [X^{m},X^{n}]^{2} + \frac{1}{2} \left(\frac{\mu}{6} \right)^{2} X_{m}^{2} \right. \\ &\left. + \frac{1}{2} \psi^{T} \mathcal{C} \left(D_{\tau} - \frac{i\mu}{4} \gamma^{567} \right) \psi - \frac{1}{2} \psi^{T} \mathcal{C} \gamma^{i} [X^{i},\psi] \right] \end{split}$$

BMN model

$$S[X,\psi] = N \int_{0}^{\beta} d\tau \operatorname{Tr} \left[\frac{1}{2} D_{\tau} X^{i} D_{\tau} X^{i} - \frac{1}{4} \left([X^{r}, X^{s}] + \frac{i\mu}{3} \varepsilon^{rst} X_{t} \right)^{2} - \frac{1}{2} [X^{r}, X^{m}]^{2} - \frac{1}{4} [X^{m}, X^{n}]^{2} + \frac{1}{2} \left(\frac{\mu}{6} \right)^{2} X_{m}^{2} + \frac{1}{2} \psi^{T} \mathcal{C} \left(D_{\tau} - \frac{i\mu}{4} \gamma^{567} \right) \psi - \frac{1}{2} \psi^{T} \mathcal{C} \gamma^{i} [X^{i}, \psi] \right]$$

BMN model



The non-perturbative phase diagram of the BMN matrix model, Y. Asano, V. G. Filev, SK, Denjoe O' Connor JHEP 1807 (2012) 154, [hep-th/1805.05314]

Bosonic BMN model

$$S[X, A] = N \int_0^\beta d\tau \operatorname{Tr} \left[\frac{1}{2} D_\tau X^i D_\tau X^i - \frac{1}{4} \left([X^r, X^s] + \frac{i\mu}{3} \varepsilon^{rst} X_t \right)^2 - \frac{1}{2} [X^r, X^m]^2 - \frac{1}{4} [X^m, X^n]^2 + \frac{1}{2} \left(\frac{\mu}{6} \right)^2 X_m^2 \right]$$

Bosonic BMN model

$$S[X, A] = N \int_0^\beta d\tau \operatorname{Tr} \left[\frac{1}{2} D_\tau X^i D_\tau X^i - \frac{1}{4} \left([X^r, X^s] + \frac{i\mu}{3} \varepsilon^{rst} X_t \right)^2 - \frac{1}{2} [X^r, X^m]^2 - \frac{1}{4} [X^m, X^n]^2 + \frac{1}{2} \left(\frac{\mu}{6} \right)^2 X_m^2 \right]$$

Bosonic BMN model

$$S[X,A] = N \int_0^\beta d\tau \operatorname{Tr} \left[\frac{1}{2} D_\tau X^i D_\tau X^i - \frac{1}{4} \left([X^r, X^s] + \frac{i\mu}{3} \varepsilon^{rst} X_t \right)^2 \right]$$

$$-\frac{1}{2}[X^{r}, X^{m}]^{2} - \frac{1}{4}[X^{m}, X^{n}]^{2} + \frac{1}{2}\left(\frac{\mu}{6}\right)^{2}X_{m}^{2}$$

- i = 1, ..., 9
- X are N x N Hermitian matrices
- $\beta = 1 / T$, inversed temperature
- D = ∂ i [A , .]
- A is the SU(N) gauge field (fixed not to depend on time and be)
- Temporal direction discretised
- Parameters: β , μ , N, Λ

Measuring (mean values of) observables

$$\langle \mathcal{O} \rangle = \frac{\int d[X] d[A] \mathcal{O} e^{-S[X,A]}}{Z}, \ Z = \int d[X] d[A] e^{-S[X,A]}$$

The setup

$$S[X,A] = N \int_0^\beta d\tau \operatorname{Tr} \left[\frac{1}{2} D_\tau X^i D_\tau X^i - \frac{1}{4} \left([X^r, X^s] + \frac{i\mu}{3} \varepsilon^{rst} X_t \right)^2 - \frac{1}{2} [X^r, X^m]^2 - \frac{1}{4} [X^m, X^n]^2 + \frac{1}{2} \left(\frac{\mu}{6} \right)^2 X_m^2 \right]$$

$$\langle \mathcal{O} \rangle = \frac{\int d[X] d[A] \mathcal{O} e^{-S[X,A]}}{Z}$$

Observables

$$N^{2}E = \langle H \rangle = -\partial_{\beta} \ln Z$$

$$C = \langle (H - \langle H \rangle)^{2} \rangle = \partial_{\beta}^{2} \ln Z$$

$$\langle |P| \rangle = \left\langle \frac{1}{N} |\text{Tr} (\exp[i\beta A])| \right\rangle$$

$$R_{ii}^{2} = \left\langle \frac{1}{N\beta} \int_{0}^{\beta} d\tau \text{Tr} (X^{i}X^{i}) \right\rangle \quad \text{(no sum on } i)$$

$$M = \left\langle \frac{i}{3N\beta} \int_{0}^{\beta} d\tau \epsilon_{rst} \text{Tr} (X^{r}X^{s}X^{t}) \right\rangle$$

What to expect?



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Hybrid Monte Carlo

Integration over **many** variables

$$\langle \mathcal{O} \rangle = \frac{\int d[X] d[A] \mathcal{O} e^{-S[X,A]}}{Z}$$

The idea is instead of computing this, we can produce a sample of configurations with the **same probability distribution** (probability sampling)



Х














Simulations results

Simulations results

$$S[X,A] = N \int_0^\beta d\tau \operatorname{Tr} \left[\frac{1}{2} D_\tau X^i D_\tau X^i - \frac{1}{4} \left([X^r, X^s] + \frac{i\mu}{3} \varepsilon^{rst} X_t \right)^2 \right]$$

$$-\frac{1}{2}[X^r, X^m]^2 - \frac{1}{4}[X^m, X^n]^2 + \frac{1}{2}\left(\frac{\mu}{6}\right)^2 X_m^2$$





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N = 32, \wedge = 24, μ = 2





Moments of the e.v. distribution

Moments of the e.v. distribution



$S_e(\{u_n\}) = S_0 + (a_1|u_1|^2 + b_1|u_1|^4 + \dots) + (a_2|u_2|^2 + b_2|u_2|^4 + \dots)$















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-3

-2

-1

0

1



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3

2
















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N = 32, \wedge = 24, μ = 2





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Let us define a convenient observable



Let us define a convenient observable

















Plots of Q



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Very accurate estimates for critical temperatures allows us to extrapolate to large-N limit ...

Very accurate estimates for critical temperatures allows us to extrapolate to large-N limit ...



... to see that there is only a single one!

Phase diagram for N = 12

*T***_{c1},** *T***_{c2}, Pade approximation**



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Just to mention: phase transitions of BMN

$$S[X,\psi] = N \int_{0}^{\beta} d\tau \operatorname{Tr} \left[\frac{1}{2} D_{\tau} X^{i} D_{\tau} X^{i} - \frac{1}{4} \left([X^{r}, X^{s}] + \frac{i\mu}{3} \varepsilon^{rst} X_{t} \right)^{2} - \frac{1}{2} [X^{r}, X^{m}]^{2} - \frac{1}{4} [X^{m}, X^{n}]^{2} + \frac{1}{2} \left(\frac{\mu}{6} \right)^{2} X_{m}^{2} + \frac{1}{2} \psi^{T} \mathcal{C} \left(D_{\tau} - \frac{i\mu}{4} \gamma^{567} \right) \psi - \frac{1}{2} \psi^{T} \mathcal{C} \gamma^{i} [X^{i}, \psi] \right]$$





Conclusions

- There is a single (1st order, confined/deconfined) phase transition for the bosonic BMN model
- There are **two different** phase transitions in the SUSY BMN model (confined/deconfined and transition into fuzzy sphere background)
- There is **yet another** phase transition in the BD model (which is hard to study numerically with satisfactory precision)
- Unsettling question: What N is large enough?

Thank you!



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 $\{N = 12, N = 24, N = 32, N = 48\}$

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