On Torsion and Curvature in Courant Algebroids

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Context and motivation

- Formulation of type II supergravities as gravity on the generalized tangent bundle (COIMBRA, STRICKLAND-CONSTABLE, WALDRAM 2011-2012) and general duality invariant gravity theories (HULL, HOHM, ZWIEBACH 2009-2013).
- Use of Courant algebroid connections, Courant algebroid-, or Gualtieri-torsion (GUALTIERI 2007) and variants of Riemann curvature (XU 2010,HOHM, ZWIEBACH 2013, JURČO, VYSOKÝ 2015).
- Compare to the definition of torsion and curvature:

For a vector bundle $E \to M$ and a connection ∇ , i.e. a degree-1 derivation of the dg module $\Omega(M, E) = \Gamma(\Lambda T^* M \otimes E)$ over $\Omega(M)$,

The curvature of ∇ is $R_{\nabla} = \nabla^2$.

In case E = TM and $\tau \in \Gamma(T^*M \otimes TM)$ the identity/solder form,

The torsion of ∇ is $T_{\nabla} = \nabla \tau$.

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Context and motivation

Alternative view on Courant algebroids:

Isomorphism classes of Courant algebroids correspond to degree-2 symplectic differential graded manifolds.

(Roytenberg, Ševera, 2002)

In this talk:

- Define the notion of connection Q_E in a graded vector bundle E over a dg manifold M.
- Find curvatue as $R_{Q_{\mathcal{E}}} = 1/2 [Q_{\mathcal{E}}, Q_{\mathcal{E}}]$ and torsion as $T_{Q_{\mathcal{E}}} = Q_{\mathcal{E}}(\tau)$ for an appropriate section τ .
- Compare these notions to standard torsion and curvature (e.g. on Lie algebroids by restricting to Dirac structures).
- The special case $\mathcal{M} = T^*[2]T[1]M$ is relevant for Courant algebroids.
- Compute Ricci and scalar curvature.

Setup: Graded vector bundles over Q-manifolds

Notations and conventions from graded geometry: As e.g. in the lectures by CATTANEO, SCHÄTZ (2010)

- \mathcal{M} denotes a graded manifold, i.e. a \mathbb{Z} -graded sheaf of commutative algebras over a smooth manifold M, locally isomorphic (in the category of \mathbb{Z} -graded algebras) to the local model $\mathcal{C}^{\infty}(U) \otimes SV$, where $U \subset M$ open in M, V a graded vector space and SV is the symmetric algebra.
- C(M) = ⊕_kC^k(M) denotes the graded commutative algebra of functions on M, i.e. global sections of the underlying sheaf.
 Vect(M) = ⊕_kVect^k(M) is the graded Lie algebra of derivations of C(M), i.e. the graded vector fields.
- E → M denotes a graded vector bundle over M, i.e. a graded manifold E together with an atlas of coordinates (y^A, s^α) such that y^A are coordinates of M (i.e. generators of the algebra of functions on the local model) and s^α transform linearly, i.e. they are fibre variables. The dual bundle is denoted by E^{*}.
- Γ(ε) ≡ C(ε^{*})_{lin} ⊂ C(ε^{*}) denotes the space of functions on ε^{*} linear in the fibre variables, i.e. the space of sections in ε.

Setup: Connection and curvature

For a Q-manifold M, i.e. a graded manifold equipped with a degree 1 cohomologial vector field Q (i.e. $Q^2 = 1/2[Q, Q] = 0$) define:

Definition (Q-connection) A Q-connection on $\mathcal{E} \to \mathcal{M}$ is a degree 1 vector field $\mathcal{Q}_{\mathcal{E}} \in \operatorname{Vect}^1(\mathcal{E}^*)$

satisfying the conditions

- $\mathcal{Q}_{\mathcal{E}}$ preserves $\Gamma(\mathcal{E})$,
- $Q_{\mathcal{E}}$ projects to Q.

We can take the commutator of $\mathcal{Q}_{\mathcal{E}}$ with itself to define the curvature:

Definition (Curvature of a Q-connection)

The curvature of a $\mathcal{Q}\text{-}connection \ \mathcal{Q}_{\mathcal{E}}$ on $\mathcal{E}\to \mathcal{M}$ is the degree 2 vector field

$$R_{\mathcal{Q}_{\mathcal{E}}} = \mathcal{Q}_{\mathcal{E}}^2 = 1/2[\mathcal{Q}_{\mathcal{E}}, \mathcal{Q}_{\mathcal{E}}] \in \operatorname{Vect}^2(\mathcal{E}^*) .$$
(1)

In case the curvature vanishes, $(\mathcal{E}, \mathcal{Q}_{\mathcal{E}})$ is called \mathcal{Q} -bundle (GRÜTZMANN, KOTOV, STROBL, 2014).

Setup: Torsion of a Q-connection

Let now \mathcal{M} be an $N\mathcal{Q}$ -manifold, i.e. there is a fibration

$$\mathcal{M} = \mathcal{M}_n \xrightarrow{p_n} \mathcal{M}_{n-1} \xrightarrow{p_{n-1}} \cdots \xrightarrow{p_2} \mathcal{M}_1 \xrightarrow{p_1} \mathcal{M}_0 \equiv \mathcal{M}.$$

•
$$p := p_1 \circ p_2 \circ \cdots \circ p_n$$
.
• $(x^{\mu}, \psi^{\alpha}, \dots)$ coordinates on \mathcal{M} .
• ψ_{α} dual to the fibre coordinates ψ^{α} .
• $s_{\alpha} := p^* \psi_{\alpha}$.
 $p^* \mathcal{M}_1 - \rightarrow \mathcal{M}_1$
 \downarrow
 \downarrow
 $\mathcal{M} \xrightarrow{p} \mathcal{M}$

Then, "tautological section" $\tau_{\mathcal{M}} = \psi^{\alpha} s_{\alpha} \in \Gamma(p^* \mathcal{M}_1) = C(p^* \mathcal{M}_1^*)$, and E.g. standard geometry, $\tau \in \Gamma(T^* M \otimes TM), \tau(X) = X, \tau = dx^{\mu} \otimes \partial_{\mu}$

Definition (Torsion of a Q-connection)

Let $\mathcal{Q}_{\mathcal{E}}$ be a connection on $\mathcal{E} = p^* \mathcal{M}_1 \to \mathcal{M}$. The torsion of $\mathcal{Q}_{\mathcal{E}}$ is the degree 1 section

$$T_{\mathcal{Q}_{\mathcal{E}}} = \mathcal{Q}_{\mathcal{E}}(\tau_{\mathcal{M}}) \in \Gamma(p^* \mathcal{M}_1) .$$
⁽²⁾

Immediate observations

- For a Lie algebroid (*M* = *A*[1], *d_A*) and a bundle *E* → *A*[1], *Q_E* gives the standard definition of a Lie algebroid connection, *Q²_E* gives the curvature of the Lie algebroid connection.
- ▶ In case $\mathcal{E} = p^* A[1]$, where $p : A[1] \to M$ is the bundle projection itself, we get the standard definition of Lie algebroid torsion.
- Now: Take the degree 2 dg manifold M = T*[2]T[1]M which encodes Courant algebroids. The Ševera class [H] ∈ H³(M) is contained as twist of the cohomological vector field. We will investigate curvature and torsion in this case.

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Graded geometry of Courant algebroids

$\mathcal{M} = T^*[2]T[1]M$

- Degree 2: $(x^{\mu}, \psi^{\mu}, b_{\mu}, p_{\mu})$ local coordinates.
- Canonical symplectic form: $\omega = dx^{\mu}dp_{\mu} + d\psi^{\mu}db_{\mu}$.
- Homological vector field is hamiltonian, $d_{\mathcal{M}} = \{\Theta, \cdot\}$, $\Theta = \psi^{\mu} p_{\mu} + \frac{1}{3!} H_{\mu\nu\rho} \psi^{\mu} \psi^{\nu} \psi^{\rho}$.

Connection and curvature

For $\mathcal{E} \to \mathcal{M},$ according to the definition, we write a connection as

$$Q_{\mathcal{E}} = d_{\mathcal{M}} + \Upsilon^{\alpha}{}_{\beta} \, s_{\alpha} \frac{\partial}{\partial s_{\beta}} \,, \tag{3}$$

and the curvature $R_{\mathcal{Q}_\mathcal{E}} = \mathcal{Q}_\mathcal{E}^2$ reads

$$R_{\mathcal{Q}_{\mathcal{E}}} = (d_{\mathcal{M}}\Upsilon^{\alpha}{}_{\beta} + (-)^{|s_{\alpha}| - |s_{\gamma}| + 1}\Upsilon^{\alpha}{}_{\gamma}\Upsilon^{\gamma}{}_{\beta})s_{\alpha}\frac{\partial}{\partial s_{\beta}}.$$
 (4)

The curvature for pullback of vector bundles

In case $E \to M$ is an ordinary vector bundle, $\mathcal{E} = p^* E[k]$,

The curvature can be expanded as:

$$R_{\mathcal{Q}_{\mathcal{E}}} = R_{\nabla} + VV + R_{\mathcal{Q}_{\mathcal{E}}}^{(1,1)}, \qquad (5)$$

- $R_{\nabla}{}^{\alpha}{}_{\beta} = (\partial_{\mu}\Gamma_{\nu}{}^{\alpha}{}_{\beta} \Gamma_{\mu}{}^{\alpha}{}_{\gamma}\Gamma_{\nu}{}^{\gamma}{}_{\beta} + \frac{1}{2}H_{\rho\mu\nu}V^{\rho\alpha}{}_{\beta})\psi^{\mu}\psi^{\nu}$ Contains ordinary curvature and twist.
- $VV^{\alpha}{}_{\beta} = -(V^{\mu\alpha}{}_{\gamma}V^{\nu\gamma}{}_{\beta})b_{\mu}b_{\nu}$ Product of endomorphisms.
- $(R^{(1,1)}_{Q_{\mathcal{E}}})^{\alpha}{}_{\beta} = (\partial_{\mu}V^{\nu\alpha}{}_{\beta} + V^{\nu\gamma}{}_{\beta}\Gamma_{\mu}{}^{\alpha}{}_{\gamma} \Gamma_{\mu}{}^{\gamma}{}_{\beta}V^{\nu\alpha}{}_{\gamma})\psi^{\mu}b_{\nu} + \underline{V^{\mu\alpha}{}_{\beta}p_{\mu}}$ Contains the *p*-dependent term.

Torsion, $\mathcal{E} = p^* \mathcal{M}_1$

In case of Courant algebroids, the fibration of graded manifolds is

$$T^*[2]T[1]M \xrightarrow{\rho_2} \mathbb{T}[1]M := (T \oplus T^*)[1]M \xrightarrow{\rho_1} M.$$

The torsion therefore is

$$T_{\mathcal{Q}_{\mathcal{E}}} = \mathcal{Q}_{\mathcal{E}}(\tau) = T_{\nabla} + T_{V} + T_{\mathcal{Q}_{\mathcal{E}}}^{(1,1)}, \qquad (6)$$

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where T_{∇} contains the standard part, T_{V} is an endomorphism and $T_{Q_{\mathcal{E}}}^{(1,1)}$ contains the degree 2 part.

Remarks: Degree 2 and sections in vector bundles

Remarks

- ▶ $R_{Q_{\mathcal{E}}} = Q_{\mathcal{E}}^2$ and $T_{Q_{\mathcal{E}}} = Q_{\mathcal{E}}(\tau)$ are global objects, but not canonically sections in vector bundles over *M*: They contain the degree 2 objects, which transform inhomogeneously, w.r.t. coordinate changes.
- ▶ Via introducing a connection ∇^{K} on M, i.e. $\nabla^{K}\partial_{\mu} = K^{\rho}{}_{\mu}\partial_{\rho}$ and $K^{\rho}{}_{\mu} = K_{\nu}{}^{\rho}{}_{\mu} \psi^{\nu}$ there's an identification

$$T^*[2]T[1]M \simeq T[1]M \oplus T^*[1]M \oplus T^*[2]M$$

- This allows to compare the global definitions to traditional geometric expressions (tensors, ordinary sections in degree shifted bundles).
- With $\tilde{p} := p + K^T b$, i.e. $\tilde{p}_{\mu} = p_{\mu} + K_{\nu}{}^{\rho}{}_{\mu} \psi^{\nu} b_{\rho}$, we separate $R_{Q_{\mathcal{E}}}^{(1,1)}$ and $T_{Q_{\mathcal{E}}}^{(1,1)}$ into a section containing K and a \tilde{p} part:

$$R_{\mathcal{Q}_{\mathcal{E}}} = R_{\mathcal{K}} + V^{\mu} \tilde{p}_{\mu} , \quad T_{\mathcal{Q}_{\mathcal{E}}} = T_{\mathcal{K}} + \tilde{p}_{\mu} s^{\mu} .$$
(7)

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Comparison to traditional geometry

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With the connection K it it turns out that for $a, b \in \Gamma(\mathbb{T}M)$

$$R_{\mathcal{K}}(\boldsymbol{a},\boldsymbol{b}) = \left[\iota_{\boldsymbol{b}}^{\mathcal{K}}\left[\iota_{\boldsymbol{a}}^{\mathcal{K}} R_{\mathcal{Q}_{\mathcal{E}}}\right]\right], \quad T_{\mathcal{K}}(\boldsymbol{a},\boldsymbol{b}) = \iota_{\boldsymbol{b}}^{\mathcal{K}}\iota_{\boldsymbol{a}}^{\mathcal{K}}(T_{\mathcal{Q}_{\mathcal{E}}}).$$
(8)
ith $\iota_{\boldsymbol{a}}^{\mathcal{K}} = \boldsymbol{a}^{\mu}\left(\frac{\partial}{\partial\psi^{\mu}} + \mathcal{K}_{\mu}{}^{\rho}{}_{\nu} \boldsymbol{b}_{\rho}\frac{\partial}{\partial\rho_{\nu}}\right) + \boldsymbol{a}_{\mu}\left(\frac{\partial}{\partial b_{\mu}} - \mathcal{K}_{\rho}{}^{\mu}{}_{\nu} \psi^{\rho}\frac{\partial}{\partial\rho_{\nu}}\right).$

We want to compare to the familiar expressions:

$$R_D(a, b) = [D_a, D_b] - D_{[a,b]_C} ,$$

$$T_D(a, b) = D_a b - D_b a - [a,b]_C .$$
(9)

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Note, for $[a, b]_C$ the Courant bracket these are not not sections in any bundle, they are not meaningful. Our apporach allows to *deduce* the terms to get well defined sections $R_K(a, b)$, $T_K(a, b)$.

Comparison to traditional geometry

Two of our main results are:

Proposition (comparison of curvature)

Let $D = \nabla + V$ be a Courant algebroid connection in a vector bundle $E \to M$, $a = X + \xi$, $b = Y + \eta$ be generalized vectors. The curvature R_{κ} reads

$$R_{\mathcal{K}}(a,b) = R_D(a,b) + V_{\tilde{\mathcal{K}}(a,b)}, \qquad (10)$$

where $\tilde{K}(a, b)$ is defined by

$$\tilde{K}(X+\xi,Y+\eta) = [X+\xi,Y+\eta]_{\mathcal{C}} - [X,Y] + \nabla_Y^{\mathcal{K}}\xi - \nabla_X^{\mathcal{K}}\eta .$$
(11)

Proposition (comparison of torsion)

Let $D = \nabla + V$ be a Courant algebroid connection in $\mathbb{T}M$, and $a = X + \xi$, $b = Y + \eta$. The torsion T_K reads

$$T_{\mathcal{K}}(a,b) = T_{\mathcal{D}}(a,b) + \tilde{\mathcal{K}}(a,b) , \qquad (12)$$

where $\tilde{K}(a, b)$ is defined by (11).

Discussion and Outlook

- We defined the notion of connection Q_E and curvature R_{Q_E} on graded vector bundles E → M over Q-manifolds M. The curvature is simply R_{Q_E} = Q²_E.
- In case of NQ-manifolds, we give a definition of torsion as derivative of the tautological section T_{Qε} = Qε(τ).
- These expressions are global by construction and give rise to ordinary tensors R_K and T_K with the help of an auxiliary connection K on the body manifold. In particular they suggest a natural way to get Courant algebroid curvature and torsion.
- For an appropriate compatibility condition on K, R_{Q_E} and T_{Q_E} give the standard Lie algebroid curvature and torsion if one restricts the bundle *E* → *M* to a Dirac structure *L* ⊂ *M*.

Discussion and Outlook

- Computation of Ricci and scalar curvature is done in the standard way by taking a trace and then contracting with a generalized metric.
- For Courant algebroids, setting the torsion T_K to zero fixes the auxiliary connection K in terms of Γ and V. Moreover D takes the simple form

$$D = \nabla + V = \begin{pmatrix} \nabla & 0 \\ H & \nabla^* \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ V & 0 \end{pmatrix}.$$
 (13)

▶ The only remaining freedom is V. Taking $V^{\rho}_{\mu\nu} := \alpha g^{\rho\sigma} H_{\sigma\mu\nu}$, we get for the scalar curvature

$$Scal(\nabla, V) = R(\nabla) - \frac{\alpha^2}{2} H^2 , \qquad (14)$$

which is interesting for e.g. string theory.