

A Connection for Born Geometry

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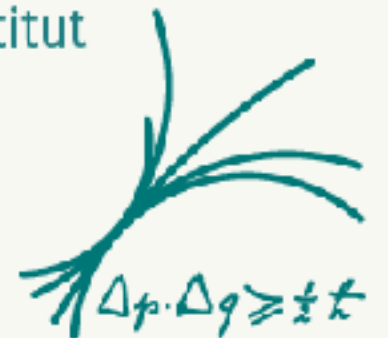
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Max-Planck-Institut
für Physik



Physics & Geometry

Geometrical Structures

symplectic geometry
Riemannian geometry
geometry of principle bundles



Physical Concepts

classical & quantum mechanics
general relativity
gauge theories

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What is the geometry for Quantum Gravity?

Context

- Consider possible geometry for "quantum gravity"
- Motivated by principles from GR and QM
- String Theory naturally lives in such geometry
- Study geometric objects such as connections, curvature, fluxes, ...

Outline

1. Introduction: Context & Motivation
2. What is Born Geometry?
3. Para-Hermitian Geometry & D-Structures
4. Born Connection
5. Outlook

What is Born Geometry?

Born Geometry

[Freidel, Minic, Leigh '14]

- Doubled Space: 2d-dimensional manifold \mathcal{P}

Born Geometry

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- Doubled Space: 2d-dimensional manifold \mathcal{P} - motivated by

→ Doubled target space (DFT) $X = \begin{pmatrix} x \\ \tilde{x} \end{pmatrix}$

Born Geometry

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→ Doubled target space (DFT) $X = \begin{pmatrix} x \\ \tilde{x} \end{pmatrix}$ $\tilde{x}' = p$

- Phase space of string

$$\text{Ham}(x, p) = \dot{x} \cdot p - \text{Lag} = \frac{1}{2} Z^T \mathcal{H} Z \quad Z = \begin{pmatrix} x' \\ p \end{pmatrix}$$

Born Geometry

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Three compatible structures on \mathcal{P}

- Generalized metric \mathcal{H}
- Neutral metric η
- (Almost) Symplectic form ω

Born Geometry

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Three compatible structures on \mathcal{P}

- Generalized metric \mathcal{H}
- Neutral metric η
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- Para-Hermitian manifold + generalized metric

String Theory

String Theory naturally lives in a Born geometry.

- Doubled Formalism
 - World sheet: Doubled String Sigma Model (Tseytlin)
 - Target space: Double Field Theory (DFT)

$$X = \begin{pmatrix} x \\ \tilde{x} \end{pmatrix}$$

with dual coordinates
defined via $\tilde{x}' = p$

Doubled String Sigma Model

includes
topological term

$$S_{\text{doubled}} = \frac{1}{2} \int d\tau d\sigma \left[(\eta_{MN} + \omega_{MN}) \partial_\tau X^M \partial_\sigma X^N - \mathcal{H}_{MN} \partial_\sigma X^M \partial_\sigma X^N \right]$$

[Tseytlin '90; Giveon, Rocek '91; Hull '06]

String sigma model action containing all three structures

- Global $O(d, d)$ symmetry manifest
- Not Lorentz invariant — impose as constraint
- Interpret target space as DFT / Born geometry

Double Field Theory

[Siegel '93; Hull & Zwiebach '09]

- Doubled Target Space

$$S_{\text{DFT}} = \int d^{2d} X e^{-2\Phi} \mathcal{R}(\mathcal{H}, \Phi)$$

Generalized
Ricci scalar

- Unification of background fields in target space

$$\mathcal{H} = \begin{pmatrix} g - Bg^{-1}B & Bg^{-1} \\ -g^{-1}B & g^{-1} \end{pmatrix}$$

- Unification of local symmetries (diffeos & gauge trafos)
 - Closure of symmetry algebra gives constraint

Connections

Riemann vs Born

Differential geometry
Riemannian manifold

“Generalized” geometry
Born manifold

Levi-Civita Connection

- Recall: Connection ∇ in Riemannian geometry (M, g)

→ Metric compatible: $\nabla_X g = 0$



Lie bracket

→ Torsion-free: $T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y] = 0$

Levi-Civita Connection

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→ Torsion-free: $T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y] = 0$

- Such a connection always exists and is unique

→ Koszul formula:

$$g(\nabla_X Y, Z) = \frac{1}{2} \left\{ X[g(Y, Z)] + Y[g(Z, X)] - Z[g(X, Y)] \right. \\ \left. + g([X, Y], Z) - g([Y, Z], X) - g([X, Z], Y) \right\}$$

Levi-Civita
connection

Riemann vs Born

Differential geometry
Riemannian manifold

- Riemannian manifold M
- Metric g
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“Generalized” geometry
Born manifold

The Unique Connection Problem

- In DFT one only considers the structures (η, \mathcal{H}) on \mathcal{P}
- Compatibility with (η, \mathcal{H}) and vanishing (generalized) torsion \mathcal{T} is not enough to fix a unique connection!
- Certain components remain undetermined

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- Compatibility with (η, \mathcal{H}) and vanishing (generalized) torsion \mathcal{T} is not enough to fix a unique connection!
- Certain components remain undetermined
- But: Generalized Ricci scalar in action is fully determined
- Issues may arise for higher order corrections
- Unsatisfactory - hints at missing ingredient

Towards the Born Connection

- Can be fixed in Born geometry!
- Missing ingredient is ω
- First need to understand **para-Hermitian** sector (η, ω) of Born geometry

Need generalized differentiable structure

Para-Hermitian Geometry

Para-Complex Manifold

- 2d-dimensional para-complex manifold (\mathcal{P}, K)
- Para-complex structure $K^2 = +1$
- Eigenbundles (of equal rank)

$$K|_L = +1 \quad K|_{\tilde{L}} = -1 \quad P, \tilde{P} = \frac{1}{2}(\mathbb{1} \pm K)$$

- Splitting of tangent space $K : T\mathcal{P} = L \oplus \tilde{L}$
- Integrability of L and \tilde{L} is independent

Para-Hermitian Manifold

- Include pseudo-Riemannian metric $\eta \Rightarrow (\mathcal{P}, \eta, K)$
- Skew-orthogonality: $K^{\top} \eta K = -\eta$
- Split signature (d, d) since eigenbundles have same rank
- Fundamental form $\omega = \eta K$ (almost symplectic)

$$\omega = \eta K = -K^{\top} \eta = -\omega^{\top}$$

- Eigenbundles L and \tilde{L} are isotropic w.r.t η and ω

Riemann vs Born

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Riemannian manifold

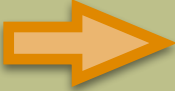
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“Generalized” geometry
Born manifold

- para-Hermitian manifold \mathcal{P}
- Structure (η, K)

D-Structure

Differentiable Structure

- Two main notions of differentiation on a smooth manifold
 - Lie derivative \mathcal{L}_X — always exists
 - Covariant derivative ∇_X — need connection
- For vector fields  Lie bracket

$$\mathcal{L}_X Y = [X, Y]$$

Differentiable Structure

- Two main notions of differentiation on a smooth manifold
 - Lie derivative \mathcal{L}_X — always exists
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- For vector fields → Lie bracket

$$\mathcal{L}_X Y = [X, Y] = \nabla_X Y - \nabla_Y X$$

any torsion-free
connection

Riemann vs Born

Differential geometry Riemannian manifold

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- Metric g
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“Generalized” geometry Born manifold

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- Structure (η, K)

D-structure

- Generalized Lie derivative

$$\mathbb{L}_X Y = \llbracket X, Y \rrbracket$$

D-bracket

- Bracket operation $\llbracket \cdot, \cdot \rrbracket$ for vector fields on $T\mathcal{P}$ with

→ Leibniz property $\llbracket X, fY \rrbracket = f \llbracket X, Y \rrbracket + X[f]Y$

- Compatible with the metric:

$$\mathbb{L}_X \eta = 0$$

not true in general
for Lie derivative

D-structure

- Compatible with $K \Rightarrow$ generalized integrability
- Eigenbundles L and \tilde{L} are Dirac structures (involutive)

$$[[L, L]] \subseteq L$$

$$[[\tilde{L}, \tilde{L}]] \subseteq \tilde{L}$$

$$\tilde{P}[[P(X), P(Y)]] = 0 \quad P[[\tilde{P}(X), \tilde{P}(Y)]] = 0$$

D-structure

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- Eigenbundles L and \tilde{L} are Dirac structures (involutive)

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D-structure

$$(\mathcal{P}, \eta, K, [[,]])$$

D-bracket $[[,]]$

- Leibniz property
- Compatible with η
- Compatible with K

[Freidel, FJR,
Svoboda '18]

Riemann vs Born

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- Structure (η, K)
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 - D-bracket \llbracket , \rrbracket

D-structure

- Can define a D-bracket for any metric-compatible connection ∇

$$\eta([X, Y]^\nabla, Z) = \eta(\nabla_X Y - \nabla_Y X, Z) + \eta(\nabla_Z X, Y)$$

D-structure

- Can define a D-bracket for any metric-compatible connection ∇

$$\eta([X, Y]^\nabla, Z) = \eta(\nabla_X Y - \nabla_Y X, Z) + \eta(\nabla_Z X, Y)$$

- Among all D-brackets, there is a **canonical** one which projects onto the Lie bracket when restricted to L and \tilde{L}

$$[[P(X), P(Y)]] = P([P(X), P(Y)])$$

$$[[\tilde{P}(X), \tilde{P}(Y)]] = \tilde{P}([\tilde{P}(X), \tilde{P}(Y)])$$

D-structure

[Freidel, FJR, Svoboda '18]

- The canonical D-bracket is unique:

Proposition

On a para-Hermitian manifold (\mathcal{P}, η, K) there exists a unique canonical D-bracket $\llbracket \cdot, \cdot \rrbracket^c$ with the above properties (Leibniz, compatibility with η and K) and which projects onto the Lie bracket $[\cdot, \cdot]$ when restricted to L and \tilde{L} .

- Note:
The bracket is unique but the connection is not, i.e. there are different connections giving the canonical bracket.

Generalized Torsion

- Ordinary torsion $T^\nabla(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y]$
- Difference between brackets $[X, Y]^\nabla := \nabla_X Y - \nabla_Y X$

Generalized Torsion

- Ordinary torsion $T^\nabla(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y]$
 - Difference between brackets $[X, Y]^\nabla := \nabla_X Y - \nabla_Y X$
- Generalized torsion

$$\mathcal{T}^\nabla(X, Y) = \llbracket X, Y \rrbracket^\nabla - \llbracket X, Y \rrbracket^c$$

- Defined in terms of the unique canonical D-bracket

Riemann vs Born

Differential geometry Riemannian manifold

- Riemannian manifold M
- Metric g
- Differentiable structure
 - Lie derivative \mathcal{L}_X
 - Lie bracket $[,]$
- Metric compatibility
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- Levi-Civita connection ∇^g

“Generalized” geometry Born manifold

- para-Hermitian manifold \mathcal{P}
- Structure (η, K)
- D-structure
 - Gen. Lie derivative \mathbb{L}_X
 - D-bracket \llbracket , \rrbracket
- Gen. torsion \mathcal{T}

Born Geometry

- Start from para-Hermitian manifold $(\mathcal{P}, \eta, \omega)$
- Include another metric $\mathcal{H} \Rightarrow (\mathcal{P}, \eta, \omega, \mathcal{H})$

→ Chiral structure $J = \eta^{-1}\mathcal{H}$

$$J^2 = +\mathbb{1}$$

Proposition

Born Geometry is equivalent to a para-Hermitian structure (η, K) along with a choice of Riemannian metric g on L .

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“Generalized” geometry Born manifold

- Born manifold \mathcal{P}
- Structures $(\eta, \omega, \mathcal{H})$
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Born Connection

Born Connection

[Freidel, FJR, Svoboda '18]

- Connection compatible with Born geometry $(\mathcal{P}, \eta, \omega, \mathcal{H})$

$$\nabla^B \eta = \nabla^B \omega = \nabla^B \mathcal{H} = 0$$

- Vanishing generalized torsion

$$\mathcal{T}^{\nabla^B} = 0$$

The Born connection exists and is unique!

(Like Levi-Civita connection for Riemannian geometry.)

Born Connection

Theorem (Freidel, FJR, Svoboda)

There exists a unique connection ∇^B compatible with the Born structure $(\eta, \omega, \mathcal{H})$ and with vanishing generalized torsion \mathcal{T} . It is given by

$$\begin{aligned}\nabla_X^B Y = & \llbracket X_-, Y_+ \rrbracket_+^c + \llbracket X_+, Y_- \rrbracket_-^c \\ & + (K \llbracket X_+, KY_+ \rrbracket^c)_+ + (K \llbracket X_-, KY_- \rrbracket^c)_-\end{aligned}$$

where $X_{\pm} = \frac{1}{2}(\mathbb{1} \pm J)X$ are the projected components associated with the splitting of $T\mathcal{P}$ given by the chiral structure J .

Born Connection

$$\begin{aligned}\nabla_X^{\text{B}} Y &= \llbracket X_-, Y_+ \rrbracket_+^c + \llbracket X_+, Y_- \rrbracket_-^c \\ &\quad + (K \llbracket X_+, KY_+ \rrbracket^c)_+ + (K \llbracket X_-, KY_- \rrbracket^c)_-\end{aligned}$$

- Lagrangian subspaces

$$K : T\mathcal{P} = L \oplus \tilde{L}$$

- Chiral subspaces

$$J : T\mathcal{P} = C_+ \oplus C_-$$

$$P_{\pm} = \frac{1}{2}(\mathbb{1} \pm J)$$

$$X_{\pm} = P_{\pm}(X)$$

Born Connection

$$\begin{aligned}\nabla_X^B Y &= \llbracket X_-, Y_+ \rrbracket_+^c + \llbracket X_+, Y_- \rrbracket_-^c \\ &\quad + (K \llbracket X_+, KY_+ \rrbracket^c)_+ + (K \llbracket X_-, KY_- \rrbracket^c)_-\end{aligned}$$

- Born geometry analogue of Koszul formula for Levi-Civita connection
- No coincidence: (L, g) is a Riemannian vector bundle recalling $P(X) = x$

Projected Born Connection

- Born geometry analogue of Koszul formula for Levi-Civita connection
- No coincidence: (L, g) is a Riemannian vector bundle recalling $P(X) = x$

Theorem

The Born connection ∇^B restricts on L to the Levi-Civita connection ∇^g of g

$$\nabla_{P(X)}^B P(Y) = \nabla_x^g y$$

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“Generalized” geometry Born manifold

- Born manifold \mathcal{P}
- Structures $(\eta, \omega, \mathcal{H})$
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Outlook

Outlook

- Make relation to DFT precise
 - ➔ Include Dilaton: need weighted bundle (tensor density)
 - ➔ Include Fluxes: obstruction to closure, integrability
- Generalized Fluxes in Born geometry
 - ➔ Twisted D-bracket: $[[,]] = [[,]]_0 + \mathcal{F}$
- Analogue of Riemann Normal Coordinates
- ...

Summary

- Born Geometry: possible geometry for Quantum Gravity
- para-Hermitian manifold + dynamical metric $(\mathcal{P}, \eta, \omega, \mathcal{H})$
- Generalized differentiable structure: D-bracket $\llbracket \cdot, \cdot \rrbracket$
- Born Connection ∇^B : unique, torsion-free, compatible
- Reduces to Levi-Civita connection ∇^g on L

Extensions

Riemann vs Born

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Born Geometry

Proposition

There always exists a frame $E \in GL(2d)$ in which the triple $(\eta, \omega, \mathcal{H})$ takes the form

$$\eta = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \omega = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \quad \mathcal{H} = \begin{pmatrix} h & 0 \\ 0 & h^{-1} \end{pmatrix}.$$

- The frame E is only determined up to an $O(d)$ trafo
- h is a constant metric on L
- Riemannian metric $g = e^T h e$

Structure Groups

$$Sp(2d) \cap O(d, d) \cap O(2d) = O(d)$$

Structure Groups

neutral metric η

Lorentz group

$$Sp(2d) \cap O(d, d) \cap O(2d) = O(d)$$

symplectic form ω

dynamical metric \mathcal{H}

Generalized Kinematics & Dynamics for DFT

Generalization

- Generalization of geometry suitable for strings in a doubled space
- Kinematical structure encoded in (η, ω)
 - ➔ Neutral metric $\eta \in O(d, d)$
 - ➔ Symplectic form $\omega \in Sp(2d)$
- Dynamical d.o.f. in generalized metric $\mathcal{H}(g, B)$

Generalizations for DFT

- DFT is limit of Born geometry
- Right setup to allow for general η and ω
- Accommodate:
 - ➔ Geometric and non-geometric fluxes
 - ➔ Non-commutativity, non-associativity, non-geometry, ...

T-Duality

T-Duality

- What is T-duality?

- Sigma model with two sets of fields x^μ and \tilde{x}_μ

- Integrate out one or the other

$$\tilde{x}' = p = \dot{x} \qquad x' = w = \dot{\tilde{x}}$$

- Get T-duality related actions

- Canonical transformation on phase space

- No need for compact dimensions or isometries

T-Duality

[Tseytlin '90, Duff '90, Siegel '93]

- Worldsheet symmetry (exchanges σ and τ)

$$dx^\mu \rightarrow *dx^\mu$$

- Target space symmetry

$$X \rightarrow J(X)$$

chiral structure

- Doubled string actions with manifest symmetry

