

Tube dislocations in gravity

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The problem: $g_{\mu\nu}(x)$ - metric

$\Gamma_{\mu\nu\rho} = \partial_{\mu}g_{\nu\rho} + \partial_{\nu}g_{\mu\rho} - \partial_{\rho}g_{\mu\nu}$ - Christoffel's symbols

$R_{\mu\nu\rho}^{\sigma} = \partial_{\mu}\Gamma_{\nu\rho}^{\sigma} - \partial_{\nu}\Gamma_{\mu\rho}^{\sigma} - \Gamma_{\mu\rho}^{\zeta}\Gamma_{\nu\zeta}^{\sigma} + \Gamma_{\nu\rho}^{\zeta}\Gamma_{\mu\zeta}^{\sigma}$ - curvature

$R_{\mu\nu} = R_{\mu\rho\nu}^{\rho}$ - Ricci tensor

$R = g^{\mu\nu}R_{\mu\nu}$ - scalar curvature

Einstein's equations:

$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R = -\frac{1}{2}T_{\mu\nu}$$

$T_{\mu\nu}$ - energy-momentum tensor

$$g \in \theta(x) = \begin{cases} 0, & x \leq 0 \\ 1, & x > 0 \end{cases} \text{ - step function} \quad \Gamma \sim \delta(x) \quad R \sim \delta^2(x) \text{ - is not defined}$$

Tube dislocation in the linear elasticity theory

\mathbb{R}^3 , x^i, y^i $i = 1, 2, 3$ - Euclidean space with Cartesian coordinates
(infinite homogeneous and isotropic elastic media
or eather in general relativity)

$\delta_{ij} = \text{diag}(+++)$ - Euclidean metric

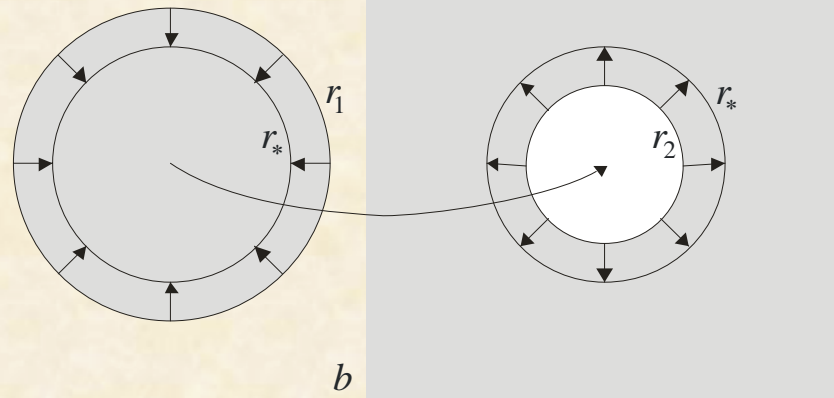
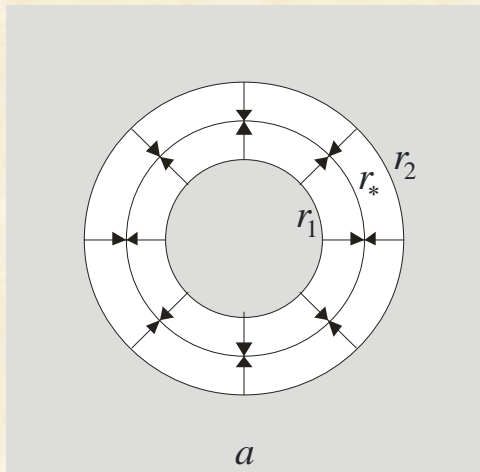
$u^i(x)$ - displacement vector field

$(1 - 2\sigma)\Delta u_i + \partial_i \partial_j u^j = 0$ - equations for the equilibrium state
(Newton's and Hook's laws)

$f^i(x) = 0$ - external forces

$\sigma = \frac{\lambda}{2(\lambda + \mu)}$ - the Poisson ratio $-1 \leq \sigma \leq \frac{1}{2}$

λ, μ - Lamé coefficients



$y^i \rightarrow x^i(y) = y^i + u^i(x)$ - definition of the displacement vector field

r, φ, z - cylindrical coordinates

u^r, u^φ, u^z - displacement vector field

$$u^\varphi = 0, \quad u^z = 0 \quad u^r = u = \begin{cases} u_{\text{in}} \\ u_{\text{ex}} \end{cases}$$

$u|_{r=0} = 0, \quad u|_{r=\infty} = 0, \quad \left. \frac{du_{\text{in}}}{dr} \right|_{r=r^*} = \left. \frac{du_{\text{ex}}}{dr} \right|_{r=r^*}$ - boundary conditions

$$\partial_r \left[\frac{1}{r} \partial_r (ru) \right] = 0$$
 - equation of equilibrium

$$u = ar - \frac{b}{r} = \begin{cases} u_{\text{in}} = ar, & a > 0, \\ u_{\text{ex}} = -\frac{b}{r}, & b > 0. \end{cases}$$
 - solution

$$l = r_2 - r_1 \quad r_* = \frac{r_2 + r_1}{2}$$

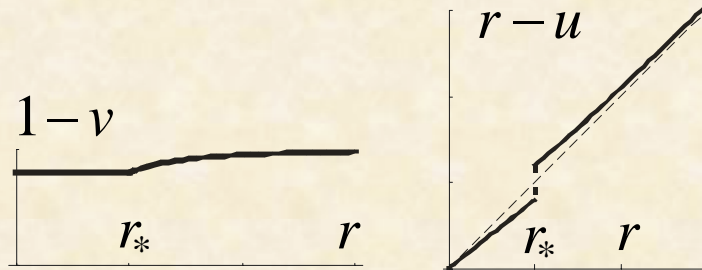
$$a = \frac{l}{2r_*}, \quad b = \frac{lr_*}{2}$$

The geometry of the tube dislocation

$$g_{\mu\nu} = \frac{\partial y^\rho}{\partial x^\mu} \frac{\partial y^\sigma}{\partial x^\nu} \hat{g}_{\rho\sigma} \quad \text{- the induced metric} \quad \hat{g}_{\rho\sigma} \quad \text{-Euclidean metric in cylindrical coordinates}$$

$$u(r) = \begin{cases} ar, & r < r_* \\ -\frac{b}{r}, & r > r_* \end{cases} \quad v(r) = \begin{cases} a, & r < r_* \\ \frac{b}{r^2}, & r > r_* \end{cases} \quad u' = v - l\delta(r - r_*)$$

$$ds^2 = (1-v)^2 dr^2 + (r-u)^2 d\phi^2 + dz^2 \quad \text{- the induced metric}$$



Scalar curvature: $\tilde{R} = \frac{2l}{(r-u)(1-v)^2} \left[\delta'(r-r_*) + \frac{v'}{1-v} \delta(r-r_*) \right]$

Einstein's equations

$$\sqrt{g} \left(\tilde{R}_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \tilde{R} \right) = -\frac{1}{2} T_{\mu\nu}$$

Energy momentum tensor

$$T_{zz} = \frac{4lr_*}{2r_* - l} \delta'(r-r_*)$$

Summary of the geometric theory of defects (physical interpretation of Riemann-Cartan geometry)

Media with dislocations and disclinations =

= \mathbb{R}^3 with a given Riemann-Cartan geometry

Independent variables $\left\{ \begin{array}{l} e_{\mu}^i \text{ - triad field} \\ \omega_{\mu}^{ij} \text{ - SO(3)-connection} \end{array} \right.$

$T_{\mu\nu}^i = \partial_{\mu} e_{\nu}^i - \omega_{\mu}^{ij} e_{\nu j} - (\mu \leftrightarrow \nu)$ - torsion (surface density of the Burgers vector)

$R_{\mu\nu}^{ij} = \partial_{\mu} \omega_{\nu}^{ij} - \omega_{\mu}^{ik} \omega_{\nu k}^j - (\mu \leftrightarrow \nu)$ - curvature (surface density of the Frank vector)

Elastic deformations: $R_{\mu\nu}^{ij} = 0, \quad T_{\mu\nu}^i = 0$

Dislocations: $R_{\mu\nu}^{ij} = 0, \quad T_{\mu\nu}^i \neq 0$

Disclinations: $R_{\mu\nu}^{ij} \neq 0, \quad T_{\mu\nu}^i = 0$

Dislocations and disclinations: $R_{\mu\nu}^{ij} \neq 0, \quad T_{\mu\nu}^i \neq 0$

The free energy

$$S = \int d^3x eL, \quad e = \det e_\mu^i$$

$$L = \kappa \tilde{R} - \gamma R_{[ij]} R^{[ij]}$$

$\tilde{R}(e)$ - the Hilbert-Einstein action

$R_{[ij]}(e, \omega)$ - antisymmetric part of Ricci tensor

equations of equilibrium
admit solutions

$$\left\{ \begin{array}{l} R = 0, \quad T \neq 0 \text{ - only dislocations} \\ R \neq 0, \quad T = 0 \text{ - only disclinations} \\ R = 0, \quad T = 0 \text{ - elastic deformations} \end{array} \right.$$

The action is invariant with respect to general coordinate transformations and local SO(3) rotations. Therefore we must fix the gauge.

Elastic gauge

$$(1 - 2\sigma)\Delta u_i + \partial_i \partial_j u^j = 0 \quad - \text{the elasticity equation}$$

$$\sigma = \frac{\lambda}{2(\lambda + \mu)} \quad - \text{Poisson ratio}$$

$$e_{\mu i} \approx \delta_{\mu i} - \partial_\mu u_i \quad - \text{the linear approximation}$$

$$(1 - 2\sigma)\partial^\mu e_{\mu i} + \partial_i e_\mu{}^\mu = 0 \quad - \text{the elastic gauge (fixes diffeomorphisms)}$$

Lorentz gauge

$$\partial^\mu \omega_\mu{}^{ij} = 0 \quad - \text{the Lorenz gauge (fixes SO(3)-invariance)}$$

If there are no disclinations $R_{\mu\nu}{}^{ij} = 0$, then $\omega_{\mu i}{}^j = l_{\mu i}{}^j = (\partial_\mu S^{-1})_i{}^k S_k{}^j$

pure gauge

$$\partial^\mu l_\mu{}^{ij} = 0 \quad - \text{principal chiral SO(3)-model}$$

Tube dislocation in the geometric theory of defects

No disclinations: $R_{\mu\nu i}{}^j = 0 \Rightarrow \omega_{\mu}{}^{ij} = 0$

$$\sqrt{|g|} \left(\tilde{R}_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \tilde{R} \right) = -\frac{1}{2} T_{\mu\nu} \quad \text{- Einstein's equations} \quad T_{zz} = L\delta'(r - r_*)$$

$$(1 - 2\sigma)\partial^{\mu} e_{\mu i} + \partial_i e_{\mu}{}^{\mu} = 0 \quad \text{- the elastic gauge} \quad L = \text{const}$$

$$ds^2 = A^2 dr^2 + B^2 d\varphi^2 + dz^2 \quad \text{- ansatz for metric}$$

$A(r), B(r)$ - unknown functions

Asymptotically flat boundary conditions: $B_{\text{in}}|_{r=0} = 0, A_{\text{in}}|_{r=0} < \infty, B_{\text{ex}}|_{r \rightarrow \infty} = r$

Matching condition: $A_{\text{in}}|_{r=r_*} = A_{\text{ex}}|_{r=r_*}$

$$ds_{\text{in}}^2 = (1 - a)^2 dr^2 + (1 - a)^2 r^2 d\varphi^2 + dz^2$$

$$ds_{\text{ex}}^2 = \left(1 - \frac{b}{r}\right)^2 dr^2 + \left(r + \frac{b}{r}\right)^2 d\varphi^2 + dz^2$$

- the exact solution coincides with the solution in elasticity theory

$$a = \frac{L}{L + 4r_*}, \quad b = \frac{Lr_*^2}{L + 4r_*}$$

Tube dislocation in general relativity

Einstein's equations:
$$\sqrt{g} \left(\tilde{R}_{\alpha\beta} - \frac{1}{2} g_{\alpha\beta} \tilde{R} \right) = -\frac{1}{2} T_{\alpha\beta}, \quad \alpha, \beta = 0, 1, 2, 3$$

$$T_{00} = -T_{zz} = L\delta'(r - r_*) \quad \text{- energy-momentum tensor}$$

$$L = \text{const}$$

$$(1 - 2\sigma)\partial^\mu e_{\mu i} + \partial_i e_\mu{}^\mu = 0$$

- the elastic gauge

The exact solution for the tube dislocation

$$ds_{\text{in}}^2 = dt^2 - (1 - a)^2 dr^2 - (1 - a)^2 r^2 d\varphi^2 - dz^2$$

$$ds_{\text{ex}}^2 = dt^2 - \left(1 - \frac{b}{r}\right)^2 dr^2 - \left(r + \frac{b}{r}\right)^2 d\varphi^2 - dz^2$$

$$a = \frac{L}{L + 4r_*}, \quad b = \frac{Lr_*^2}{L + 4r_*}$$

Conical tube dislocation

Einstein's equations:

$$\sqrt{g} \left(\tilde{R}_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \tilde{R} \right) = -\frac{1}{2} T_{\mu\nu} \quad \mu, \nu = 1, 2, 3$$

$$T_{zz} = \Theta \delta(r - r_*) - \text{the source} \quad \Theta = \text{const}$$

$$(1 - 2\sigma) \partial^\mu e_{\mu i} + \partial_i e_\mu{}^\mu = 0$$

- the elastic gauge

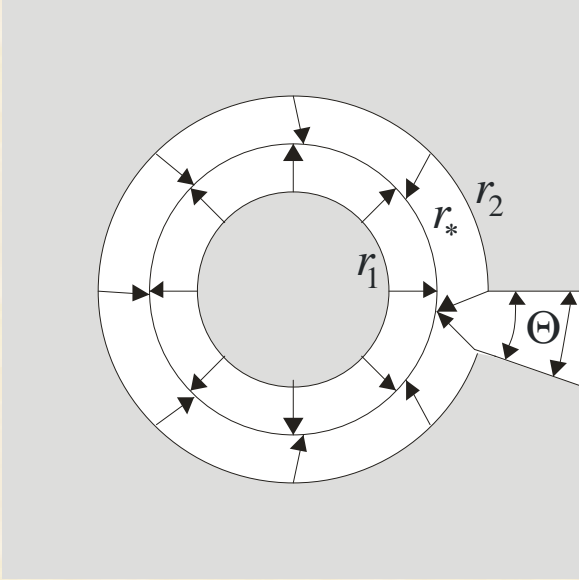
r, φ, z - cylindrical coordinates $0 \leq r \leq R$

$$ds^2 = A^2 dr^2 + B^2 d\varphi^2 + dz^2 - \text{ansatz for the metric}$$

$$\text{Boundary conditions: } B_{\text{in}}|_{r=0} = 0, \quad A_{\text{in}}|_{r=0} < \infty, \quad A_{\text{ex}}|_{r=R} = 1$$

$$\text{Matching condition: } A_{\text{in}}|_{r=r_*} = A_{\text{ex}}|_{r=r_*}$$

Solution for the conical tube dislocation



$$ds^2 = A^2 dr^2 + B^2 d\varphi^2 + dz^2 \text{ - the exact solution}$$

$$A = \begin{cases} D, & 0 \leq r \leq r_* \\ \frac{1}{\alpha} \left(E_1 \gamma_1 r^{\gamma_1 - 1} + E_2 \gamma_2 r^{\gamma_2} \right), & r_* \leq r \leq R \end{cases}$$

$$B = \begin{cases} Dr, & 0 \leq r \leq r_* \\ E_1 r^{\gamma_1} + E_2 r^{\gamma_2}, & r_* \leq r \leq R \end{cases}$$

$$\alpha = 1 + \Theta, \quad \Theta \text{ - the deficit angle}$$

$$\gamma_1 > 0, \quad \gamma_2 < 0 \text{ are the roots of the equation } \gamma^2 + \frac{\Theta \sigma}{1 - \sigma} \gamma - \alpha = 0$$

$$D = \frac{\alpha}{\gamma_1 \frac{\alpha - \gamma_2}{\gamma_1 - \gamma_2} \left(\frac{R}{r_*} \right)^{\gamma_1 - 1} - \gamma_2 \frac{\alpha - \gamma_1}{\gamma_1 - \gamma_2} \left(\frac{R}{r_*} \right)^{\gamma_2 - 1}}$$

$$E_1 = D \frac{\alpha - \gamma_2}{\gamma_1 - \gamma_2} r_*^{-\gamma_1 + 1}, \quad E_2 = -D \frac{\alpha - \gamma_1}{\gamma_1 - \gamma_2} r_*^{-\gamma_2 + 1}$$

Asymptotically flat wedge dislocation

Einstein's equations:

$$\sqrt{g} \left(\tilde{R}_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \tilde{R} \right) = -\frac{1}{2} T_{\mu\nu} \quad \mu, \nu = 1, 2, 3$$

$$T_{zz} = -\Theta \delta(r - r_*) \text{ - the source} \quad \Theta = \text{const}$$

$$(1 - 2\sigma) \partial^\mu e_{\mu i} + \partial_i e_\mu{}^\mu = 0$$

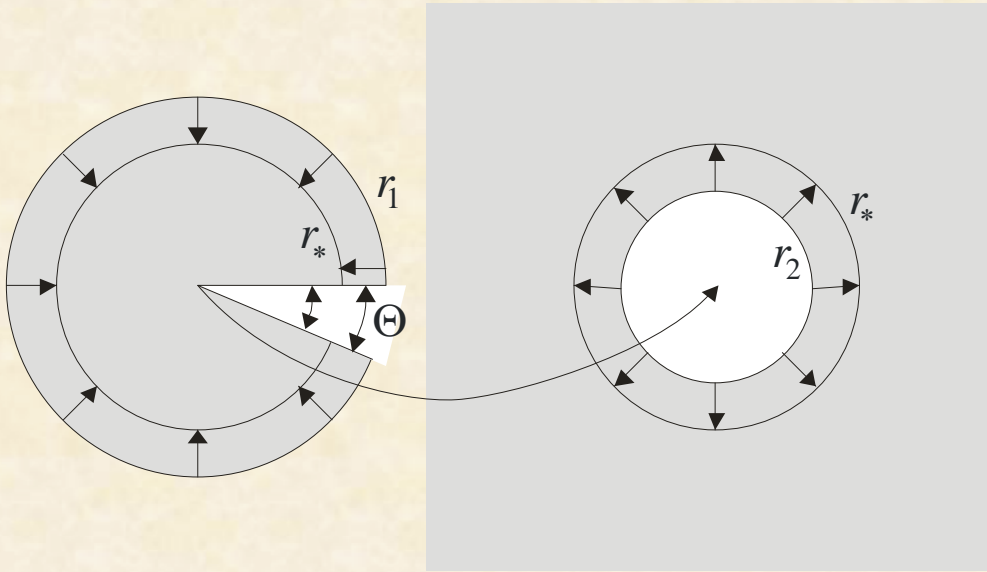
- the elastic gauge

r, φ, z - cylindrical coordinates

$$\text{Boundary conditions: } B_{\text{in}}|_{r=0} = 0, \quad \frac{rA_{\text{in}}}{B_{\text{in}}}\bigg|_{r=0} = \frac{\gamma_1}{\alpha} \text{ - conical singularity at the origin}$$
$$A_{\text{ex}}|_{r=\infty} = 1 \text{ - asymptotic flatness}$$

$$\text{Matching condition: } A_{\text{in}}|_{r=r_*} = A_{\text{ex}}|_{r=r_*}$$

Solution for the asymptotically flat tube dislocation



$$\alpha = 1 + \Theta, \quad \Theta - \text{the deficit angle}$$

$$\Theta < 0 - \text{the wedge is cut out}$$

$$2\pi\alpha r_1 = 2\pi r_2 - \text{the continuity of metric components}$$

The exact solution:

$$ds_{\text{in}}^2 = \frac{4\gamma_1^2}{(\alpha + \gamma_1)^2} \left(\frac{r}{r_*} \right)^{2\gamma_1 - 2} \left(dr^2 + \frac{\alpha^2}{\gamma_1^2} r^2 d\varphi^2 \right) + dz^2$$

$$ds_{\text{ex}}^2 = \left[1 - \frac{\alpha - \gamma_1}{\alpha + \gamma_1} \left(\frac{r_*}{r} \right)^2 \right]^2 dr^2 + \left[1 + \frac{\alpha - \gamma_1}{\alpha + \gamma_1} \left(\frac{r_*}{r} \right)^2 \right]^2 r^2 d\varphi^2 + dz^2$$

$$\gamma_1 > 0 \text{ is the positive root of the equation } \gamma^2 + \frac{\Theta\sigma}{1-\sigma}\gamma - \alpha = 0$$

Continuous distribution of tube dislocations

Einstein's equations:

$$\sqrt{g} \left(\tilde{R}_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \tilde{R} \right) = -\frac{1}{2} T_{\mu\nu} \quad \mu, \nu = 1, 2, 3$$

$$T_{zz} = 2f(r) \quad \text{- the source term} \quad f(r) \quad \text{- an arbitrary function}$$

$$ds^2 = A^2 dr^2 + B^2 d\varphi^2 + dz^2 \quad \text{- ansatz for the metric}$$

Einstein's equations:

$$\left(\frac{B'}{A} \right)' = f(r)$$

$$\text{The exact solution: } B = \int_0^r ds A(s) \int_0^s dt f(t) + c_1 \int_0^r ds A(s) + c_2 \quad c_{1,2} = \text{const}$$

$$\text{The boundary condition: } B \Big|_{r=0} = 0 \quad \Rightarrow \quad c_2 = 0$$

$$\frac{B'}{A} \Big|_{r=0} = 1 \quad \Rightarrow \quad c_1 = 1$$

$$\text{The elastic gauge: } \frac{B''}{F} - \frac{B'f}{F^2} + \frac{B'}{Fr} - \frac{B}{r^2} + \frac{\sigma}{1-2\sigma} \left(\frac{B''}{F} - \frac{B'f}{F^2} + \frac{B'}{r} - \frac{B}{r^2} \right) = 0$$

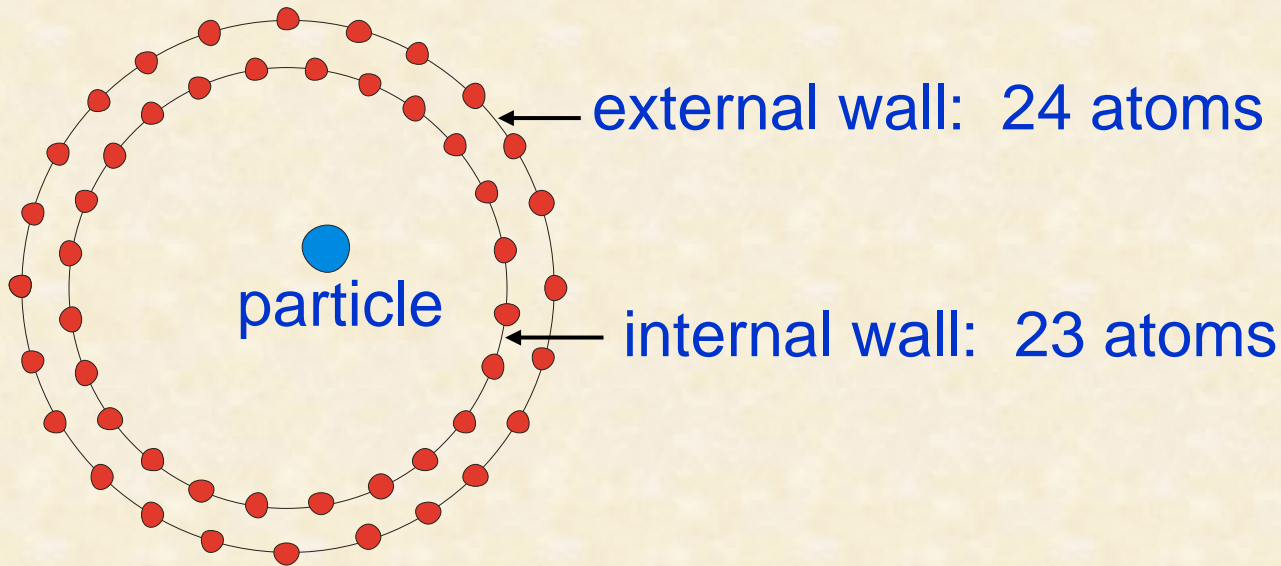
$$F(r) = \int_0^r ds f(s)$$

Conclusion

- 1) A new family of exact solutions of Einstein's equations is found
- 2) Physical interpretation of solutions: tube dislocations
- 3) Metric components or its derivatives are discontinuous functions
- 4) All ambiguous terms in Einstein's equations cancel
- 5) The source term (energy-momentum tensor) is proportional to $\delta'(r)$ or $\delta(r)$

May tube dislocations
have any applications ?

Double wall nanotube



Motion of a quantum particle inside a nanotube

$$i\hbar \frac{\partial \psi}{\partial t} = -\frac{\hbar^2}{2m} \Delta \psi \quad \longrightarrow \quad i\hbar \frac{\partial \psi}{\partial t} = -\frac{\hbar^2}{2m} \frac{1}{\sqrt{g}} \partial_\mu \left(\sqrt{g} g^{\mu\nu} \partial_\nu \psi \right) + U\psi$$